

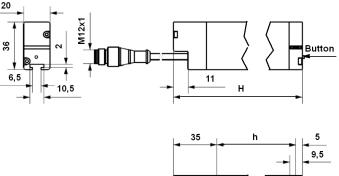
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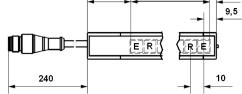
DESCRIPTION OF THE IO_LINK FUNCTIONS FOR THE CR SERIES

Foreword

The intent of this document is to describe the structure and the operation mode of the CR sensor with the aim to clarify the constraints that determine the possible functions and availability of data.

The CR IO-Link series is currently made up of three models: CR0, CR1, CR2, whose main characteristics are described below, but for complete information please also consult the User Manual of the specific model:





Pc.:1

MODEL	OPTICAL PITCH	OPTICAL HEIGHT	BODY HEIGTH	EMITTERS	RECEIVERS	OPTICS	BEAM PAIRS	REFLECTOR RANGE	RESPONSE TIME LIGHT / DARK DARK / LIGHT	SWITCHING FREQUENCY	PIG TAIL CONNECTOR	POLES	PIN	INTERFACE Only programmable via IO-Link		
	Р	h	н	En	Rn	On	Вр	Rr	Tr	f max	Туре	No	No	I/O	MODE C: comunication	
ARTICLE	mm	mm	mm	N°	N°	N°	N°	m	ms	Hz					Q: (SIO)	
CR0/0I-1V	10	69	109	4	3	7	6	0.2 4.5	1,97 / 2,30 (Jitter)	IO- Link 240 SIO 269			4	Output	C Q: PNP or NPN; DO or LO	
CR1/0I-1V	10	149	187	8	7	15	14	0.2 4.5	2,40 / 3,85 (Jitter)	IO- Link 220 SIO	M12 M	4	2	Output	Q: PNP or NPN; DO or LO	
								-	(Jiller)	260				Input	Remote Teach-in	
CR2/0I-1V	10	309	347	16	15	31	30	0,2 4,5	3,48 / 5,94 (Jitter)	10- Link 140 SIO 160			1	Supply Common	1830V _{DC}	
				Т	bl.:1				. ,	100				Tbl.:2		

The sensors have an optics made up of a **9x9mm lens** in a linear array with a pitch of **P (10mm)**. The optical window has a height of **h**. Emitter and Receiver are alternate with the following sequence: **E1**, **R1**, **Ex**, **Rx**, **Ex**, **Rn**, **En**, referring to the cable side. This allows to realize a continuous succession of **Bp beam pairs** of emitted and receiving beams.

To minimize the scan time, the pulses emitted are only equal to the number of emitters En, but receivers signal are equal to Bp.

For these reasons, the set point variables are only En for the transmitter current and Bp for the detection thresholds.

To optimize sensor performance under all conditions we provide a very large part of the dynamics of the amplifiers and drive currents to equalize the **Bp** different sensitivities. With a good equalization it is possible to obtain a uniform behaviour over the entire height of the optics and a great tolerance to misalignment.

Equalization is performed each time the Teach-in functions are activated.

Below we describe IODD in detail, referring to a generic CR model for simplicity.

The models differ only in the number of optics, therefore in the following data:

Process Data Input, in which the number of bits of which the "Beam Status" is formed varies.

Parameter, in which the number of Emitter Set Points and Receiver Set Point Threshold varies.

Beam Mode, the number of configurations varies.

See details in the specific chapter.

easing automation challenges

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CR SERIES IO-Link POLARIZED RETROREFLECTIVE SENSOR ARRAY **IO-LINK PARAMETER**

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A PROCESS DATA a Process data input Data Mapping Configuration, 5 tem displayed: 3 fixed (#); 2 of 9 config, 6 can determine alarm 1 Triggered *A In Light condition the ratio signal/fight thresholds, is not lower the Margin Level High Multiplier. Light status critic 2 Proximity Alarm *A In Dark condition the ratio signal/fight thresholds, is not lower the Margin Level Low Multiplier. Dark status critic 3 Margin Low Alarm *A In Dark condition the ratio signal/fight thresholds, is not lower the Margin Level Low Multiplier. Dark status critic 4 Excess Gain A Average ratio between Light signals and Light thresholds. 5 Received Signal Strength A Strength of the received at calibration (on reflector) to current levels (usually 21, a 0 means <1) 7 Temperature Current internal temperature of the device. Beam Status (Dark Bit=1) 8 Beam Status (Dark Bit=1) Status of active baces. Status of active baces of the received signal for the device. 10 Counter Value Count of the number of Light/Dark switches per second (Ir). To Moration must be enabled 12 On Duration Duration of the last Dark state (in ms, max 4095). Timer and Timer ON Duration must be enabled 13 Received Signal Off Av	al	p,8,13 p8,13; 114,22 p8,7; 114,22 p7,8,13; 114,22 p6,9,16; 116,22 p8,13; 114,22 p6,9,16; 116,22 p8,13; 114,22 p8,11,16; 114,20,22 p8,16; 114,22 p7,8,16; 113,14,22 p8,10,13; 115,19,22 p8,10; 114,16,22 p9,16; 114,16,22 p9,16; 114,16,22 p8,9,16; 114,16,22 p9,14,12; 17,22
1 Triggered *^ Pin 4 Output State, True (ON); False (OFF) 2 Proximity Alarm *^ In Dark condition the ratio signals/(light thresholds, is not over the Margin Level Light Multiplier. Dark status critic 3 Margin Low Alarm *^ In Dark condition the ratio signals/(light thresholds, is not lower the Margin Level Low Multiplier. Dark status critic 4 Excess Gain ^ Average ratio between Light signals and Light thresholds. 5 Received Signal Strength ^ Strength of the received signals 6 Contrast Level ^ Ratio of levels received at calibration (on reflector) to current levels (usually ≥1, a 0 means <1) 7 Temperature Current internal temperature of the device. 8 Beam Status (Dark Bit=1) Status of active beams. Sum of the binary weight. Different Byte length and Byte number for CR0, 1, 2. 9 Speed Number of Light/Dark (bot 4095) Timer and Timer ON Duration must be enabled 11 Ori Duration on Duration of the last Light state (in ms, max 4095). Timer and Timer ON Duration must be enabled Device monitoring 1 Pin 2 Output Command to set the ON or OF state (if enabled, see D6) See O6) 2 Green LED Command to set the ON or OF state (if enabled, see D6) OE/SE/AVATION a Device monitoring	al	p8,13; 114,22 p8,7; 114,22 p7,8,13; 114,22 p8,9,16; 116,22 p8,9,16; 116,22 p8,9,16; 114,22 p8,11,16; 114,20,22 p8,11,16; 114,20,22 p7,8,16; 113,14,22 p7,8,16; 113,14,22 p7,8,16; 113,14,22 p7,8,16; 113,14,22 p5,8,13; 115,22 p8,10,13; 115,19,22 p8,10,13; 115,19,22 p8,16; 116,22 p9,9,16; 116,22 p8,9,16; 116,22 p8,9,16; 116,22 p8,9,16; 116,22 p8,9,16; 116,22 p8,9,16; 116,22 p8,9,16; 113,12,22 p1,4,6,13,14; 19,22 p5,14; 110,22
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3 Red LED Command to set the ON or OFF state (if enabled, see Db5) B Optical parameter coming from the sensor 1 Received Signal On Average of the signals received by the active optics in Light 2 Received Signal Off Average of the signals received by the active optics in Dark 3 Contrast Level Average Ratio between taught Light signal levels (on reflector) and the current Dark signals. 4 Excess Gain Average Ratio between taught Light signal levels (on reflector) and the current Dark signals. a User Interface Config. Local Parametrization 1 Device Access Locks Unlock/Lock: Local and remote: Teach.in; Sensing Configuration; excluding Work Frequency. b Operation Configuration Define optical and I/O parameter 1 Set point memitter Allows you to change the power of the 4 (CR0), 8 (CR1), 16 (CR2) emitters 2 Set Point Thresh. Receiver Allows you to change the type of pin 4 output: Light or Dark operate 4 Output Mode Allows you to change the type of pin 4 output: Light or Dark operate 4 Output Mode Pin 2 functions: Disable; PN/PNP; LO/DO; Remote Teach-in input; ON/OFF command (see Ab1) c Sensor Configuration Define optical and typeresis of 20%.		p8.10,13; t15,19,22 (P)ag / (T)bl p9.16; t16,22 p8,9,16; t16,22 p8,9,16; t14,16,22 p6,9,16; t16,22 (P)ag / (T)bl p3,4,12 p4,12; t7,22 p4,5 p1,4,6,13,14; t9,22 p5,14; t10,22
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2 Received Signal Off Average of the signals received by the active optics in Dark 3 Contrast Level Average Ratio between taught Light signal levels (on reflector) and the current Dark signals. 4 Excess Gain Average Ratio between the current Light signal levels (on reflector) and the current Dark signals. 4 Excess Gain Average Ratio between the current Light signal levels and the Light Thresholds. 7 PARAMETER a User Interface Config. Local Parametrization 1 Device Access Locks Unlock/Lock: Local and remote: Teach.in; Sensing Configuration; excluding Work Frequency. b Operation Configuration Define optical and I/O parameter 1 Set point emitter Allows you to change the power of the 4 (CRO), 8 (CR1), 16 (CR2) emitters 2 Set Point Thresh. Receiver Allows you to change the type of pin 4 output: Light or Dark operate 4 Output Mode Allows you to change the type of pin 4 output: PNP or NPN 5 Hysteresis Reports the actual value (%) 6 Pin 2 Mode Pin 2 functions: Disable; PNP/NPN; LO/DO; Remote Teach-in input; ON/OFF command (see Ab1) 1 Working Frequency Define the optical structure, the detection parameter, command of various automatic calibrati		p9,16; t16,22 p8,9,16; t14,16,22 p6,9,16; t16,22 (P)ag / (T)bl p3,4,12 p4,12; t7,22 p4,5 p1,4,6,13,14; t9,22 p1,5,13;14; t9,22 p5,14; t10,22
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c Sensor Configuration Define the optical structure, the detection parameter, command of various automatic calibrati 1 Working Frequency Define working frequency 1 or 2 to avoid mutual interference between two sensors. 2 Beam Mode Select the number of enabled optic (Blanking) and the Beam logic AND or OR (Object or Hole detection) 3 Teach Background 1° step: Sets emitters to receive the maximum signal from the reflector 4 Teach Target 2° step: Set the threshold of the receivers to ½ of the difference, if it is not possible, apply a Teach Precision 5 Teach Standard Set a margin of 1.5 and a hysteresis of 20%. 6 Teach Precision Set a margin of 1.1 and a hysteresis of 12%. 7 Margin Booster Proposed After a teach-in it is possible to apply a proportional incr. of the margin (proportional increase of the LED current) 8 Apply Margin Multiplier Command that applies the proposed margin, if this is too high it applies the maximum possible. 9 Appled Margin Displays the margin applied.	ons	p5,6,14; t10,22
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3 Teach Background 1° step: Sets emitters to receive the maximum signal from the reflector 4 Teach Target 2° step: Set the threshold of the receivers to ½ of the difference, if it is not possible, apply a Teach Precision 5 Teach Standard Set a margin of 1.5 and a hysteresis of 20%. 6 Teach Precision Set a margin of 1.1 and a hysteresis of 12%. 7 Margin Booster Proposed After a teach-in it is possible to apply a proportional incr. of the margin (proportional increase of the LED current) 8 Apply Margin Multiplier Command that applies the proposed margin, if this is too high it applies the maximum possible. 9 Applied Margin Displays the margin applied.		p0, 11,22 p1,4,6,14,15; t11,22
4 Teach Target 2° step: Set the threshold of the receivers to ½ of the difference, if it is not possible, apply a Teach Precision 5 Teach Standard Set a margin of 1.5 and a hysteresis of 20%. 6 Teach Precision Set a margin of 1.1 and a hysteresis of 12%. 7 Margin Booster Proposed After a teach-in it is possible to apply a proportional incr. of the margin (proportional increase of the LED current) 8 Apply Margin Multiplier Command that applies the proposed margin, if this is too high it applies the maximum possible. 9 Appled Margin Displays the margin applied.	1	p6,12; t12,22
6 Teach Precision Set a margin of 1.1 and a hysteresis of 12%. 7 Margin Booster Proposed After a teach-in it is possible to apply a proportional incr. of the margin (proportional increase of the LED current) 8 Apply Margin Multiplier Command that applies the proposed margin, if this is too high it applies the maximum possible. 9 Appled Margin Displays the margin applied.	2	p6,12; t12,22
7 Margin Booster Proposed After a teach-in it is possible to apply a proportional incr. of the margin (proportional increase of the LED current) 8 Apply Margin Multiplier Command that applies the proposed margin, if this is too high it applies the maximum possible. 9 Applied Margin Displays the margin applied.		p6,12; t12,22
8 Apply Margin Multiplier Command that applies the proposed margin, if this is too high it applies the maximum possible. 9 Applied Margin Displays the margin applied.	1	p5,6,12; t12,22
9 Applied Margin Displays the margin applied.	2	
	3	
		p6,12; t12,22
11 Margin Level High Multiplier Used to define the level of the light signal which, if not reached, generates an alarm (see Aa2)		P6,7,16; T12,22
d Counter and Timer Define the Counter and Timer function		p7,8,11,12,16
1 Counter Enable Enable or disable the Light/Dark transaction counting function 2 Counter Reset Set the Counter Value to 0.		p,7,16; t13,22 p7,12; t13,22
3 Counter Value On request display the reached count of Light / Dark transitions (from 0 to 4095)		p7,12, 113,22 p7,8,16; t13,14,22
4 Timer Enable/Disable timer function		p7,16; t13,22
5 Timer Mode Delays switch. from Light/Dark or Dark/Light, or Pulse on a Light/Dark transition, or Display last Light and Dark du	ration	p7,16; t13,22
6 Timer Value Defines the duration of the actual timer functions, accepts value from 0 to 50000ms 7 Timer Reset Set to 0 the following Timer On Duration and Timer Off Duration		p7,16; t13,22
7 Timer Reset Set to 0 the following Timer On Duration and Timer Off Duration 8 Timer On Duration Display the duration of the last Light state (values from 0 to 4095ms)		p7,12; t13,22 p7,8,16; t13,14,22
9 Timer Off Duration Display the duration of the last Dark state (values from 0 to 4095ms)		p7,8,16; t13,14,22
e Data Mapping Configuration Defines the data display mode in the Process Data window (see A)		p7,8; t14,15
Process Data In Mode You can choose five different combinations of data to display (See Aa)		p8,16; t14,22
2 Process Data Output It is possible to directly control Output 2 and the signaling LEDs (See Ab)		p5,8,13; t15,22
D DIAGNOSIS a Diagnosis Display error events		(P)ag / (T)bl p8,9,10,11; t17,18,20
1 Error Count Shows the Total Error Counter		p0,0,10,11,11,10,20
2 Device Status Shows the Device Status		p9,13; t17,22
3 Detailed Device Status [1] Shows, in circular list, the first event happened		p9,13; t17,22
4 Detailed Device Status [2] Shows, in circular list, the second event happened 5 Detailed Device Status [3] Shows, in circular list, the third event happened		p9,13; t17,22
5 Detailed Device Status [3] Shows, in circular list, the third event happened 6 Detailed Device Status [4] Shows, in circular list, the fourth event happened	—	p9,13; t17,22 p9,13; t17,22
b Service Function Enable Disable Service Function		
1 Restore Factory Setting Restore a standard config. that allows you to work in the most extreme conditions		p4,10,11,12; t7,18,22
2 Local Indicator Enables/disables the Red and Green LEDs to flash at a frequency of 1Hz to help locate the sensor	III	1 - 1 - 1 - 1 - 1
3 LEDs Operation Enables/disables all LED functions 4 Alignment Mode Enable/Disable the Green/Red LEDs to have a direct/inverse proportional intensity to the received signal		1 - 1 - 1 - 1 - 1
4 Alignment Mode Enable/Disable the Green and Red LEDs to have a direct/inverse proportional intensity to the received signal 5 LEDs contr. Fr. Proc. data Enable/Disables the Green and Red LEDs to be driven by a Process Data command (see Ab2,3)	1	
c Operation Information Enable Disable Operation Information		p11,16; t20,22
1 Oper. Hours since Inception Shows total operating hours since manufacture.		P11,16; t20,22
Oper. Hours since Pow-Up Shows the hours of operation since the last power up. Eaching Discable temporature Information		P11,16; t20,22
d Temperature Enable Disable temperature Information 1 Temperature Actual Shows the current internal temperature of the sensor		p8,11,16; t14,20,22 p8,11,16; t14,20,22
Image: Temperature Actual Shows the current internal temperature of the sensor Image: Temperature Actual Shows the maximum internal temperature of the sensor Image: Temperature Actual Shows the maximum internal temperature of the sensor Image: Temperature Actual Shows the maximum internal temperature of the sensor		p11,16; 20,22
3 Temp. Max since Inception Shows the maximum internal temperature reached by the sensor since manufacture		p11,16; 20,22
4 Temp. Min since Power-Up Shows the minimum internal temperature reached by the sensor since the last power up		p11,16; 20,22
5 Temp. Min since Inception Shows the minimum internal temperature reached by the sensor since manufacture		p11,16; 20,22
e Speed 1 Actual speed Shows the actual frequency of the changing status of the C/Q output in Hz		p8,11,16; t14,20,22 p8,11,16; t14,20,22
2 Max Speed Since Power-Up Shows the maximum frequency of the changing status of the C/Q output in Hz since the power-up		p8,11,16; t14,20,22
f Event Configuration Event Configuration Event Configuration		p0,11,10,114,20,22
		p11,16; t20,22
1 Ev on local theresh. change Enables/Disables the indication that a local Teach-in has been performed		p6,7,11,16; t20,22
1 Ev on local theresh. change Enables/Disables the indication that a local Teach-in has been performed 2 Event on Low Margin Enables/Disables the indication that a low margin Light/Dark switching has occurred (see Aa3)		p6,7,11,16; t20,22
1 Ev on local theresh. change Enables/Disables the indication that a local Teach-in has been performed 2 Event on Low Margin Enables/Disables the indication that a low margin Light/Dark switching has occurred (see Aa3) 3 Event on Teach Error Enables/Disables the indication that a Teach-in has not been successful		p11,16; t20,22 p11,16; t20,22
1 Ev on local theresh. change Enables/Disables the indication that a local Teach-in has been performed 2 Event on Low Margin Enables/Disables the indication that a low margin Light/Dark switching has occurred (see Aa3) 3 Event on Teach Error Enables/Disables the indication that a Teach-in has not been successful 4 Event on Temperature Enables/Disables the indication that a temperature limit has been reached		
I Ev on local theresh. change Enables/Disables the indication that a local Teach-in has been performed 2 Event on Low Margin Enables/Disables the indication that a low margin Light/Dark switching has occurred (see Aa3) 3 Event on Teach Error Enables/Disables the indication that a Teach-in has not been successful 4 Event on Temperature Enables/Disables the indication that a temperature limit has been reached 5 Temp. Event Trigger Low Set the Temperature at which the Event "Device temperature under-run" is generated.		p11.10; [20.22
1 Ev on local theresh. change Enables/Disables the indication that a local Teach-in has been performed 2 Event on Low Margin Enables/Disables the indication that a low margin Light/Dark switching has occurred (see Aa3) 3 Event on Teach Error Enables/Disables the indication that a Teach-in has not been successful 4 Event on Temperature Enables/Disables the indication that a temperature limit has been reached 5 Temp. Event Trigger Low Set the Temperature at which the Event "Device temperature under-run" is generated.		p11,16; t20,22 p11,16; t20,22
I Ev on local theresh. change Enables/Disables the indication that a local Teach-in has been performed 2 Event on Low Margin Enables/Disables the indication that a low margin Light/Dark switching has occurred (see Aa3) 3 Event on Teach Error Enables/Disables the indication that a Teach-in has not been successful 4 Event on Temperature Enables/Disables the indication that a temperature limit has been reached 5 Temp. Event Trigger Low Set the Temperature at which the Event "Device temperature over-run" is generated. 6 Temp. Event Trigger High Set the Temperature at which the Event "Device temperature over-run" is generated		

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CR SERIES IO-Link POLARIZED RETROREFLECTIVE SENSOR ARRAY IO-LINK PARAMETER

 Language:
 EN

 Pages:
 17

 Code:
 806001120

 Date:
 13/10/2023

	moedddaenang.com
	CAL LAYER CRIPTION
IO-Link Revision	1.1
SIO Mode	YES
Min Cycle Time	1.2 ms
Transmission Rate	COM3 (230.4 kbit/s)
Process Data Length	PDInput: 5 Bytes PDOutput: 8 Bits
M-Sequence Capability	PREOPERATE = TYPE_1_V with 8 octets on-request data OPERATE = TYPE_2_V with 2 octets on-request data ISDU supported

	FEATURE DESCRIPTION										
Data Storage	YES										
Supported Access Locks	Parameter: YES, Data Storage: yes, Local Parametrization: yes, Local User Interface: no										
Profile Characteristic	Device Profile: Smart Sensor Function Class: Device Identification Function Class: Switching Signal Channel Function Class: Device Diagnosis Function Class: Teach Channel										
Tbl.:5											

Tbl.:4

						IDENTIFIC	CATION PARAMETER					
Parameter Name	Index	Index dec	Subindex	Length B/b	Access	Data Type	Value/Range	Description				
Device Information												
Vendor Name	0x0010	16		64B	ro	StringT	Datasensing S.r.l.	Informative				
Vendor Text	0x0011	17		64B	ro	StringT	Easing automation challenges					
Product Name	0x0012	18		64B	ro	StringT	It differs depending on the series or model CR0/0I-1V CR1/0I-1V CR2/0I-1V	Detailed product name Beam pairs: 6 Beam pairs: 14 Beam pairs: 30				
Product ID	0x0013	19		64B	ro	StringT	It differs by model CR0/0I-1V; CR1/0I-1V; CR2/0I-1V;	Specific model Device ID: 0x0007D1 Device ID: 0x0007D2 Device ID: 0x0007D4				
Product Text	0x0014	20		64B	ro	StringT	Retroreflective Area Sensor	Sensing Technologies				
Serial Number	0x0015	21		16B	ro	StringT	0000000	None				
User Specific Inform	ation											
Application Specific Tag	0x0016	24		32B	rw	StringT	***	Available to the operator (application)				
User Tag 1	0x0017	120		16B	rw	StringT_16		Available to the operator (where installed)				
User Tag 2	0x0018	121		16B	rw	StringT_16		Available to the operator (where installed)				
Revision Information	1											
Hardware Version	0x0019	22		64B	ro	StringT	1.0	It may depend on the model				
Firmware Version	0x001A	23		64B	ro	StringT	1.1	It may depend on the model				

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				DI	VICE SPECIE	IC PARAN	IETER						
Variable ID	Name	Index	SubIndex	BitOffset	DataType	Values Ranges	Single values	Access	Default Value		м	D	E
User Interface Configura	atios												
V_DeviceAccessLocks	Device Access Locks	12	0		RecordT			rw					
	Local Parameterization	12	3*	2	BooleanT		Locked (true) 00 04, Unlocked (false) 00 00			00 00			

Tbl.:7 User Interface Configuration •

Device Access Locks. Local Parameterization: ٠

 [00]: UnLocked: Teach button, Remote Teach Input (if selected), all other teach-in mode, Apply Margin Multiplier, Beam Mode are enabled.
 [04]: Locked: Teach button, all other teach mode, Apply Margin Multiplier, and Beam Mode are disabled. An activation of the Remote Teach Input is indicated by the signaling LEDs, but not performed. Restore Factory Setting remain active and, if done, unlocks everything, and deselect Remote Teach Input. ٠

				D	EVICE SPECI	FIC PARAN	IETER					
Variable ID	Name	Index	SubIndex	BitOffset	DataType	Values Ranges	Single values	Access	Default Value	м	D	E
Operation Configurati	ios											
						CR0						
/_SetPointEmitter1	Set Point Emitter 1	64	0		UIntegerT_16	0 to 1023		rw	767	'		
/_SetPointEmitter2	Set Point Emitter 2	65	0		UIntegerT_16	0 to 1023		rw	767	,		
/_SetPointEmitter3	Set Point Emitter 3	66	0		UIntegerT_16	0 to 1023		rw	767	'		
/_SetPointEmitter4	Set Point Emitter 4	67	0		UIntegerT_16	0 to 1023		rw	767	'		
					Added for	or CR1 model						
/_SetPointEmitter5	Set Point Emitter 5	68	0		UIntegerT_16	0 to 1023		rw	767	'		
/_SetPointEmitter6	Set Point Emitter 6	69	0		UIntegerT_16	0 to 1023		rw	767	'		
/_SetPointEmitter7	Set Point Emitter 7	131	0		UIntegerT_16	0 to 1023		rw	767	'		
/_SetPointEmitter8	Set Point Emitter 8	132	0		UIntegerT_16	0 to 1023		rw	767	'		
					Added for	or CR2 model						
V_SetPointEmitter9	Set Point Emitter 9	150	0		UIntegerT_16	0 to 1023		rw	767	'		
/_SetPointEmitter10	Set Point Emitter 10	151	0		UIntegerT_16	0 to 1023		rw	767	'		
/_SetPointEmitter11	Set Point Emitter 11	152	0		UIntegerT_16	0 to 1023		rw	767	'		
/_SetPointEmitter12	Set Point Emitter 12	153	0		UIntegerT_16	0 to 1023		rw	767			
/_SetPointEmitter13	Set Point Emitter 13	154	0		UIntegerT_16	0 to 1023		rw	767			
/_SetPointEmitter14	Set Point Emitter 14	155	0		UIntegerT_16	0 to 1023		rw	767	·		
/_SetPointEmitter15	Set Point Emitter 15	156	0		UIntegerT_16	0 to 1023		rw	767	'		
	Set Point Emitter 16	157	0		UIntegerT_16	0 to 1023		rw	767	'		T

I bl.:8

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Operation Configuration (Set Point Emitter)

The setpoints of the emitters are automatically updated as best as possible with the Teach-in command, therefore, the Set Point values should only be modified for welldefined and non-standard performances.

The emitter set points are factory set to 767. The available range is between 0 and 1023. This data defines the emission LED currents. By setting the emission currents to 0, the LEDs do not dim completely because a test current remains active (this is a separate function from the emission current). Setting the current too high or too low would not allow automatic variations thereof which have the purpose of compensating the emission following variations in the ambient temperature. When performing Teach-in, the value 767 is never exceeded. Manually modifying the current value also alters the sensitivity equalization obtained automatically with Teach-in.

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		DEVICE SPEC	IFIC F	ARA	METER							
Variable ID	Name	Index	SubIndex	BitOffset	DataType	Values Ranges	Single values	Access	Default Value	м	D	E
Operation Configuratios											_	
			CR0									
V SetPointThreshold Receiver1 1	Set Point Threshold Receive	r11 7	0 0		UIntegerT 16	0 to 4095		rw	900		,	<u> </u>
V SetPointThreshold Receiver1 2	Set Point Threshold Receive	_	-		UIntegerT 16	0 to 4095		rw	900			1
V_SetPointThreshold Receiver2_2	Set Point Threshold Receive	r2_2 7	2 (UIntegerT_16	0 to 4095		rw	900			
V_SetPointThreshold Receiver2_3	Set Point Threshold Receive	r 2_3 7	3 (UIntegerT_16	0 to 4095		rw	900			1
V_SetPointThreshold Receiver3_3	Set Point Threshold Receive	r 3_3 7	4 0		UIntegerT_16	0 to 4095		rw	900			1
V_SetPointThreshold Receiver3_4	Set Point Threshold Receive	r 3_4 7	5 0		UIntegerT_16	0 to 4095		rw	900			
		Added	for CR1	model								
V_SetPointThresholdReceiver4_4	Set Point Threshold Receive	r 4_4 12	3 (UIntegerT_16	0 to 4095		rw	900			T
V_SetPointThresholdReceiver4_5	Set Point Threshold Receive	r 4_5 12	4 0		UIntegerT_16	0 to 4095		rw	900			
V_SetPointThresholdReceiver5_5	Set Point Threshold Receive	r 5_5 12	5 0		UIntegerT_16	0 to 4095		rw	900			1
<pre></pre>	Set Point Threshold Receive	r 5_6 12	6 0		UIntegerT_16	0 to 4095		rw	900			1
V_SetPointThresholdReceiver6_6	Set Point Threshold Receive	r 6_6 12	7 (UIntegerT_16	0 to 4095		rw	900			
V_SetPointThresholdReceiver6_7	Set Point Threshold Receive	r 6_7 12	8 0		UIntegerT_16	0 to 4095		rw	900			
V_SetPointThresholdReceiver7_7	Set Point Threshold Receive	r 7_7 12	9 0		UIntegerT_16	0 to 4095		rw	900			
V_SetPointThresholdReceiver7_8	Set Point Threshold Receive	r 7_8 13	0 0		UIntegerT_16	0 to 4095		rw	900			
		Added	for CR2	model								
V_SetPointThresholdReceiver8_8	Set Point Threshold Receive	r 8_8 13	3 (UIntegerT_16	0 to 4095		rw	900)		Т
V_SetPointThresholdReceiver8_9	Set Point Threshold Receive	r 8_9 13	4 0		UIntegerT_16	0 to 4095		rw	900)		
	Set Point Threshold Receive	r 9_9 13	5 0		UIntegerT_16	0 to 4095		rw	900)		
V_SetPointThresholdReceiver9_10	Set Point Threshold Receive	r 9_10 13	6 0		UIntegerT_16	0 to 4095		rw	900)		
/_SetPointThresholdReceiver10_10	Set Point Threshold Receive	r 10_10 13	7 (UIntegerT_16	0 to 4095		rw	900)		
V_SetPointThresholdReceiver10_11	Set Point Threshold Receive	r 10_11 13	8 0		UIntegerT_16	0 to 4095		rw	900)		
V_SetPointThresholdReceiver11_11	Set Point Threshold Receive	r 11_11 13	9 0		UIntegerT_16	0 to 4095		rw	900)		
/_SetPointThresholdReceiver11_12	Set Point Threshold Receive	r 11_12 14	0 0		UIntegerT_16	0 to 4095		rw	900)		
/_SetPointThresholdReceiver12_12	Set Point Threshold Receive	r 12_12 14	1 0		UIntegerT_16	0 to 4095		rw	900)		
/_SetPointThresholdReceiver12_13	Set Point Threshold Receive	r 12_13 14	2 (UIntegerT_16	0 to 4095		rw	900)		
/_SetPointThresholdReceiver13_13	Set Point Threshold Receive	r 13_13 14	-		UIntegerT_16	0 to 4095		rw	900			
/_SetPointThresholdReceiver13_14	Set Point Threshold Receive		-		UIntegerT_16	0 to 4095		rw	900			
/_SetPointThresholdReceiver14_14	Set Point Threshold Receive	r 14_14 14	5 (UIntegerT_16	0 to 4095		rw	900)		
/_SetPointThresholdReceiver14_15	Set Point Threshold Receive	r 14_15 14			UIntegerT_16	0 to 4095		rw	900)		
/_SetPointThresholdReceiver15_15	Set Point Threshold Receive	r 15_15 14	7 (UIntegerT_16	0 to 4095		rw	900)		
/_SetPointThresholdReceiver15_16	Set Point Threshold Receive	r 15_16 14	8 (UIntegerT_16	0 to 4095		rw	900)		

Tbl.:9

Operation Configuration (Set Point Threshold Receivers)

The Set Point Threshold Receivers are automatically updated as best as possible with the Teach-in command; therefore, the Set Point values should only be modified for well-defined and non-standard performances.

The Set Point Threshold Receivers are factory set to 900. The available range is between 0 to 4095 this is the Dark threshold; the Light threshold is calculated from the actual Hysteresis. The user can set the dark threshold level from 0 to 3000, higher values may not leave space for the Light threshold.

				DE\	ICE SPECI	FIC PARA	METER					
Variable ID	Name	Index	SubIndex	BitOffset	DataType	Values Ranges	Single values	Access	Default Value	м	D	Е
Operation Configuration								<u> </u>				
V_SetPointPolarity	Polarity	76	0		UIntegerT_8		Not Inverted (LO) (0), Inverted (DO) (1)	rw	0			
_OutputMode	Output Mode	77	0		UIntegerT_8		PNP(0), NPN(1)	rw	0			
V_SetPointHysteresis	Hysteresis	78	0		UIntegerT_16			ro				
V_Pin2Mode	Pin 2 Mode	79	0		UIntegerT_8		Disable (0), PNP (LO) (1), PNP (DO) (2), NPN (LO) (3), NPN (DO) (4), Remote Teach Input (5), IndependentOuput PNP (6), IndependentOuput NPN (7)	rw	0			

Tbl.:10

Polarity: It defines the behavior of the output C/Q on pin 4 (obviously usable only in SIO mode):

- [0]: Not Inverted: (LO): means closed in Light (Not inverted). Factory Setting.
- [1]: Inverted: (DO): means closed in the Dark (Inverted).
- Output Mode: It defines the type of output C/Q on pin 4:
 - [0]: PNP (output closes towards the positive): Factory Setting.
- [1]: NPN (output closes towards the negative).
- Hysteresis: return value. Difference between Light threshold and Dark threshold expressed as %, depends on the type of Teach: 20% Automatically selected with Tech Standard (factory setting) or 12% with Teach Precision.
 - Pin 2 Mode: drop down menu. It defines the complex functions of Pin 2:
 - [0]: Disable: Clears any selection. Pin 2 is not internally connected, Factory Setting.
 [1]: PNP (LO): Pin 2 as output, closes towards the positive in Light.
 [2]: PNP (DO): Pin 2 as output, closes towards the positive in Dark.

 - [3]: NPN (LO): Pin 2 as output, closes towards the negative in Light.
 - [4]: NPN (DO): Pin 2 as output, closes towards the negative in Dark.

[5]: Remote Teach Input: Pin 2 as input. if connected to the positive, it works like pressing the Teach button (that is not excluded).

[6]: IndependentOutput PNP: Selects pin 2 as PNP output and enable the Master to switch it ON / OFF. selecting the state in Process Data Output Pin 2 Output as [1] True / [0] False. [7]: IndependentOutput PNP: Selects pin 2 as NPN output and enable the Master to switch it ON / OFF selecting the state in Process Data Output: Pin 2 Output as [1] True / [0] False.

DATASENSING S.R.L. Strada S. Caterina, 235, 41122 Modena (Italy) Tel: +39 059 420411 Fax: +39 059 253973 www.datasensing.com info@datasensing.com					CR SERIES IO-Link POLARIZED RETROREFLECTIVE SENSOR ARRAY IO-LINK PARAMETER DEVICE SPECIFIC PARAMETER							EN 17 6001 /10/2	120	
						FIC PARA	METE	R						
Variable ID	Name	Index	SubIndex	BitOffset	DataType	Values Ranges		Single valu	es	Access	Default Value	м	D	E
Sensorn Configuratios					-									
V_WorkingFrequency	Working Frequency	y 87	' (0	UIntegerT_8		1(0),2	(1)		rw	0			
				-	Only for t	ne CR0 mode	el							
							AND	From 6 Beams	To 1 Beam					
V BeamMode	Beam Mode	80)	0	UIntegerT_8			From Data [0]	To Data [5]	rw	0	х		
beaminede	Beammoue			Ũ			OR	From 6 Beams	To 1 Beam			~		
								From Data [8]	To Data [13]					
				-	Only for t	ne CR1 mode	el							
							AND	From 14 Beams	To 1 Beam					
V BeamMode	Beam Mode	80		0	UIntegerT 8			From Data [0]	To Data [13]	rw	0	х		
Deaminioue	Beammode	00	1	Ũ	ontegen_o		OR	From 14 Beams	To One Beam		0	~		
							ÖN	From Data [16]	To Data [29]					
					Only for t	ne CR2 mode	el					-		
							AND	From 30 Beams	To 1 Beam					
V BeamMode	Beam Mode	80		0	UIntegerT 8			From Data [0]	To Data [29]	rw	0	х		
-Deamwoode	Beam Moue	80	Ί	Ŭ	Sinceger 1_0		OR	From 30 Beams	To 1 Beam	1 00	0	Â		
Tbl.:11							U.	From Data [32]	To Data [61]					

Sensor Configuration

- Working Frequency: In some applications, where it is necessary to place two sensors very close together, they could interfere with each other (the emission of one could interfere with the receivers of the other). To counteract this, two different program cycle times (1) and (2) can be selected to avoid synchronization of the detection.
- Beam Mode: It defines the number of active beams and the logic function applied to the state of these, considering the Light status as 1 and the Dark as 0. Selecting the AND function allows the detection of objects, selecting the OR function allows the detection of holes. Factory Set to: AND, 6 pair (CR0), 14 pair (CR1), 30 pair (CR2).

After a Beam Mode change (AND/OR/Blanking), a partial reset of the factory settings is automatically performed, which only affects the set points of the emitters and all the receivers, the set of the excluded emitters goes to 0, that of the non-excluded ones goes to the value of 767; all receiver threshold sets go to 900. It is recommended to perform a Teach-in and possibly reset the parameters for the specific application. Now, following the Teach-in, the set of excluded receivers also goes to 0. From the button menu it is not possible to modify the set logic (AND or OR), you can only deactivate the optics (Blanking) consecutively, starting from the first (cable side), after having deactivated the penultimate pair (only one optic remains active), in the next step, all pairs are reactivated. By exiting the Blanking button menu, even without having made any changes, a partial factory calibration is performed which only concerns the set points of the active emitters and receivers, for which it is advisable to carry out a Teach-in and possibly set the parameters for the specific application.

		D	DEVIC	E SPE	CIFIC PAR	AMETER						
Variable ID	Name	Index	SubIndex	BitOffset	DataType	Values Ranges	Single values	Access	Default Value	м	D	E
Sensorn Configuratios										_		
Standard Command	Teach Background	2	0		UIntegerT_8	160	160	WO		Х		
Standard Command	Teach Target	2	0		UIntegerT_8	161	161	WO		Х		
Standard Command	Teach Standard	2	0		UIntegerT_8	162	162	WO		Х		
Standard Command	Teach Precision	2	0		UIntegerT_8	163	163	wo		Х		
V_MarginBoosterProposed	Margin Booster Proposed	81	0		UIntegerT_8	10-100		rw	10	Х		
Standard Command	Apply Margin Multiplier	2	0		UIntegerT_8	166	166	wo				
V_MarginBoosterApplied	Applied Margin	82	0		UIntegerT_8	10-200		ro		Х		
V_MarginLevelLowMultiplier	Margin Level Low Multiplier	83	0		UIntegerT_8	0-3	0.8(0), 0.7(1), 0.6(2), 0.5(3)	rw	0	Х		
V_MarginLevelHighMultiplier	Margin Level High Multiplier	84	0		UIntegerT_8	10-150	1.0(10), 1.1(11), 1.2 (12),1.5(15), 2.0(20), 5.0(50), 10.0(100), 15.0(150)	rw	12	х		

Tbl.:12

- Teach Background, command. First step of a two-step teach-in; see also Teach Target. Teach on reflector, the optical path must be free. If the alignment is enough, this command adjusts the LED currents to obtain the maximum signal received by the reflector.
- Teach Target command. Second step of a two-step teach-in. The optical path can be occupied by a completely opaque or semitransparent medium. This is the second phase and you do not have to run an alignment. This command sets the Dark threshold to 1/2 of the difference between the currently read value and the one previously read in Teach Background; hysteresis is set to 12%. If there is no signal change from that seen in Teach Background, set the same value as the Teach Precision command. If it is not possible to detect the target with certainty using the double command, re-execute the double command without introducing the target to the second, the result will be the maximum sensitivity equivalent to a Teach Precision.
- Teach Standard command. First this command adjusts the LED currents to obtain the maximum signal received by the reflector, then sets the thresholds of the active receivers to have a margin of 1.5 and a hysteresis of 20%.
- Teach Precision command. First this command adjusts the LED currents to obtain the maximum signal received by the reflector, then sets the thresholds of the active receivers to have a margin of 1.1 and a hysteresis of 12%.
- Margin Booster Proposed value to enter. This variable is expressed in tenths, it indicates the multiplier factor that will be applied to the present value of the LEDs current, enter a value and then run the Apply Margin Multiplier command.
- Apply Margin Multiplier command. This command increases the LEDs current by multiplying the present values for the Margin Booster Proposed. (e.g. with a value of 12, the factor is 1.2 times) then the new "Set Point Emitter n" value are displayed, if the calculated current value is greater than the maximum applicable value (767), even for just one of the LEDs, a smaller multiplication factor is applied to maintain sensitivity equalization. It is advisable to execute this command after performing a Teach so that the LED currents and receiver thresholds have already been adapted to obtain sensitivity equalization. This command works effectively if the LED current values are low, i.e. the reflector is not close to the minimum or maximum distance, where the
- equalization. This command works effectively if the LED current values are low, i.e. the reflector is not close to the minimum or maximum distance, where the response of the reflector is low therefore the LED current may have already reached a value equal to or close to the maximum possible. This command is useful for increasing the **Excess Gain** obtained automatically with a Teach-in, it is suitable to use a greater signal margin if the environment is
- subject to the presence of dust, or if the detection of semi-transparent objects must be excluded.
 Applied Margin; return value. It indicates the multiplier factor that has been applied. If the user run multiple commands, a cumulative value is not indicated, but only that applied to the last command. If you want to have the true margin applied, you should first run a Teach-in and then re-execute the command with a different
- Margin Level Low Multiplier. Values can be selected from 0.5, 0.6, 0.7, 0.8; Factory Set to: 0.8. If the signal received from the beams in Dark does not reaches a value below the indicated fraction of the Dark Threshold, this means that the detection of the Dark condition is becoming critical. To determine an alarm condition, the condition must remain for one hundred program cycles. If "Event on Low Margin" is enabled (on), in IO-Link mode the event is indicated with a message



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CR SERIES IO-Link POLARIZED RETROREFLECTIVE SENSOR ARRAY IO-LINK PARAMETER

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Code:	806001120
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"0x1820 : Low Margin : Event occurs when a Margin Low Alarm (Process Data) is issued" This data is displayed in all combinations of the Process Data Input window as "Margin Low Alarm". Note: Currently, only when the device is in Dark, this condition is calculated, by the ratio between the sum of the signals of the beams in Dark and the sum of the Dark thresholds of the same beams.

Margin Level High Multiplier. Values can be selected from 1.0, 1.1, 1.2, 1.5, 2.0, 5.0, 10.0, 15.0; Factory Set to: 1.0. If the signal received from the beams in Light does not reach a higher value of the factor indicated than the Light Threshold, this means that the light state detection is becoming critical. To determine an alarm condition, the condition must remain for one hundred program cycles. This alarm condition does not cause an "Event on Low Margin". This data is displayed in all combinations of the Process Data Input window as "Proximity Alarm". Note: Currently, only when the device is in Light, this condition is calculated, by the ratio between the sum of the signals of the beams in Light (in this case all the active beams) and the sum of the Light thresholds of the same beams.

			DE	VICE	SPECIFIC P	ARAMET	TER					
Variable ID	Name	Index	SubIndex	BitOffset	DataType	Values Ranges	Single values	Access	Default Value	м	D	E
Counter / Timer		•			_	_	-	•				
V_CounterEnable	Counter Enable	85	0		UIntegerT_8	0; 1	Disable (0), Enabled (1)	rw	0			
V_SystemCommand	Counter Reset	2	0		UIntegerT_8	164	164	wo		Х		
V_CounterValue	Counter Value	86	0		UIntegerT_16	0-4095		ro				
V_TimerEnable	Timer	88	0		UIntegerT_8	0; 1	Disable (0), Enabled (1)	rw	0	Х		
V_TimerMode	Timer Mode	89	0		UIntegerT_8	0, 1, 3, 4	On Delay (0); Off Delay (1); One Shot (3); Timer Duration (4)	rw	0			
V_TimerValue	Timer Value	90	0		UIntegerT_16	0 to 50000		rw	0			
V_SystemCommand	Timer Reset	2	0		UIntegerT_8	165	165	wo		Х		
V_TimerOnDuration	Timer On Duration	91	0		UIntegerT_16	0 to 4095		ro				
V_TimerOffDuration	Timer Off Duration	92	0		UIntegerT_16	0 to 4095		ro				

Tbl.:13

- Counter / Timer
- Counter Enable:
 - [0]: Disable the count function. Factory set condition. [1]: Enable counting Light to Dark transitions.
- Standard command: Counter Reset command. Set the Counter Value to 0.
 Bestoring the factory set conditions does not reset the count but disable the count of the set of the count but disable the count of the set of the count but disable the count of the set of t
- Restoring the factory-set conditions does not reset the count but disable the counter.
 Counter Value: return value. On request display the reached count. Factory set to 0.
- Timer
 - [0]: Disabled: Disables the Timer functions. Factory set condition.
 - [1]: Enabled: Enables Timer functions.
- Timer Mode. The timings act on both outputs C (2) and (4) and on the status transmitted by IO-Link.
 [0] ON Delay: Delays switching from Light to Dark state (re-triggerable). Factory set condition. Not interrupted by timer reset.
 [1] OFF Delay: Delays switching from Dark to Light state (re-triggerable). Not interrupted by timer reset.
 [3] One Shot: Transition from Light to Dark State generates a Dark Pulse (not re-triggerable). Not interrupted by timer reset.
 [4] Timer Duration: Enables display of the duration of the last Light and Dark state.
- Timer Value: Value to enter. Accepts values from 0 to 50,000ms.
- It defines the duration of the functions: ON Delay; OFF Delay; One Shot.
- Timer Reset: Command. Set to 0 Timer On Duration and Timer Off Duration.
 Timer On Duration; return value. Display the duration of the last Light state (values from 0 to 4095ms). It is also displayed in
 Process Data Input if selected in Data Mapping Configuration.
- Timer Off Duration; return value. Display the duration of the last Dark state (values from 0 to 4095ms). It is also displayed in the Process Data Input if selected in Data Mapping Configuration.

See also Tbl.:23 Pag.:17.

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CR SERIES IO-Link POLARIZED RETROREFLECTIVE SENSOR ARRAY **IO-LINK PARAMETER**

Language: EN Pages: 17 Code:

Date:

806001120 13/10/2023

			DA		APPING C	ONFIGURAT	ION					
	PROCESS	DATA	INPL	JT (Y	'ou can cho	ose betwee	n five display modes)					
Variable ID	Name	Index	SubIndex	BitOffset	DataType	Values Ranges	Single values	Access	Value	м	D	E
V_ProcessDataInMode	Process Data In Mode	93	0		UIntegerT_8	0,1,2,3,4	0	rw	Default 0			
V_ProcessDataInput		40	0*		RecordT			ro			х	
	Triggered	40	1*	32	BooleanT	0, 1	false (false), true (true)	ro				
	Proximity Alarm	40	2*	33	BooleanT	0, 1	false (false), true (true)	ro				
	Margin Low Alarm	40	3*	34	BooleanT	0, 1	false (false), true (true)	ro				
	Excess Gain	40	4*	16	UIntegerT 8			ro				
	Received Signal Strength	40	5*	0	UIntegerT 16			ro				
V_ProcessDataInMode	Process Data In Mode	93	0		UIntegerT_8	0,1,2,3,4	1	rw	Selection 1			
V_ProcessDataInput		40	0*		RecordT			ro			х	
	Triggered	40	1*	32	BooleanT	0, 1	false (false), true (true)	ro				
•	Proximity Alarm	40	2*	33	BooleanT	0, 1	false (false), true (true)	ro				
	Margin Low Alarm	40	3*	34	BooleanT	0, 1	false (false), true (true)	ro				
	Excess Gain	40	4*	16	UIntegerT 8	,		ro				
•	Contrast Level	40	5*	8	UIntegerT 8			ro				
	Temperature (Actual)	40	6*	0	UIntegerT 16	-128 to 127		ro				
V ProcessDataInMode	Process Data In Mode	93	0		UIntegerT 8	0,1,2,3,4	2	rw	Selection 2			
V_ProcessDataInput		40	0*		RecordT			ro			х	
Note: CR0, CR1, CR2	Triggered	40	1*	32	BooleanT	0, 1	false (false), true (true)	ro				
Note: CR0, CR1, CR2	Proximity Alarm	40	2*	33	BooleanT	0, 1	false (false), true (true)	ro				
Note: CR0, CR1, CR2	Margin Low Alarm	40	3*	34	BooleanT	0, 1	false (false), true (true)	ro				
Note: CR0, CR1	Beam Status *	40	4*	16	IntegerT 8	0-63, 0-16383	Note: One Byte for CR0, CR1	ro				
Note: CR0, CR1	Speed	40	5*	0	UIntegerT 16	0 to 833	<i>i i</i>	ro				
Note: CR2	Beam Status High *	40	4*	16		0-16383		ro				
Note: CR2	Beam Status Low *	40	5*	0		0-65535	Note: Two Byte for CR2	ro				
V ProcessDataInMode	Process Data In Mode	93	0		UIntegerT_8	0,1,2,3,4	3	rw	Selection 3			
V ProcessDataInput		40	0		RecordT			ro			х	
Note: CR0, CR1, CR2	Triggered	40	0*	32	BooleanT	0, 1	false (false), true (true)	ro				
Note: CR0, CR1, CR2	Proximity Alarm	40	1*	33	BooleanT	0, 1	false (false), true (true)	ro				
Note: CR0, CR1, CR2	Margin Low Alarm	40	2*	34	BooleanT	0.1	false (false), true (true)	ro				
Note: CR0, CR1	Excess Gain	40	3*	16	UIntegerT 8	,		ro				
Note: CR2	Speed	40	4*	16	UIntegerT 16	0 to 833		ro				
Note: CR0, CR1, CR2	Counter Value	40	5*	0		0 to 4095	1	ro				
V ProcessDataInMode	Process Data In Mode	93	0		UIntegerT_8	0,1,2,3,4	4	rw	Selection 4			
V ProcessDataInput		40	0*		RecordT	-, , ,-,-		ro			х	
	Triggered	40	1*	32	BooleanT	0, 1	false (false), true (true)	ro				
	Proximity Alarm	40	2*	33	BooleanT	0, 1	false (false), true (true)	ro				
	Margin Low Alarm	40	3*	34	BooleanT	0, 1	false (false), true (true)	ro				
	Timer Off Duration	40	4*	16	UIntegerT 8	0 to 4095		ro	1			
	Timer On Duration	40	. 5*	0		0 to 4095	1	ro				
			3	. <u> </u>		2 10 1000				1	·	

Tbl.:14 * The status of the receivers is expressed in Bits: Light=0, Dark=1; CR0 and CR1 use one Byte, CR2 uses two Bytes; the Low Byte expresses the receivers from 1 to 16, the High Byte expresses the receivers from 17 to 30. CR0 uses 6 Bits, CR1 uses 14 Bits, CR2 uses 30 Bits. Bit 0 of the low byte corresponds to receiver 1.

Process Data Input, this sector displays in real time selected data coming from the device. To get a description and how to change the selected data go to:

Parameter window.

• **Data Mapping Configuration**

Process Data In Mode (select one of five). The selected mode remains active at Power OFF/On. Factory Reset condition: [0].

0 [0]; [1]; [2]; [3]; [4]

	DATA MAPPING CONFIGURATION													
	PROCESS DATA OUPUT (Take control of Output 2 and the signaling LEDs)													
Variable ID	Name	Index	SubIndex	BitOffset	DataType	Values Ranges	Single values	Access	Default Value	м	D	E		
V_ProcessDataOutput	Process Data Output	41	0		RecordT			ro			х			
	Pin 2 Output	41	1	2	BooleanT	0, 1	false (false), true (true)							
	Green LED	41	2	1	BooleanT	0, 1	false (false), true (true)							
	Red LED	41	3	0	BooleanT	0, 1	false (false), true (true)							

Tbl.:15

To run the Pin 2 Output commands,

you must already have or make the relevant selections in:

- Parameter window
- **Operation Configuration**
- Pin 2 Mode (select one)
- [6] "IndependentOutput PNP" [7] "IndependentOutput NPN"
- Now you can run the command:
 - **Process Data Output**
 - Pin 2 Output (select) •
 - [0] False: Switch OFF Pin 2 output.
 - [1] True: Switch ON Pin 2 output.

To run the Green LED/Red LED commands from Master, you must already have or make the relevant selections in:

- **Diagnosis window**
- Service Function •
- LEDs control from Process Data (select True)
- [0] False "Disabled." •
- [1] True "Enabled"
- Now you can run the command:
 - **Process Data Output**
 - Green LED (select) •
 - [0] False: Switch OFF [1] True: Switch ON
 - •
 - Red LED (select)
 - [0] False: Switch OFF • •

	OB:	SERV	ATIO	N (Displays	selected c	lata on request)					
Name	Index	SubIndex	BitOffset	DataType	Values Ranges	Single values	Access	Default Value	м	D	E
Received Signal On	94	0		UIntegerT_16			ro				
Received Signal Off	95	0		UIntegerT_16			ro				
Contrast Level	96	0		UIntegerT_8			ro				
Excess Gain	97	0		UIntegerT_8			ro				
Excess Gain Resolution	98	0		UIntegerT_8		1.0 (0), 0.1 (1)	rw	0			
	Received Signal On Received Signal Off Contrast Level Excess Gain	NameSolutionReceived Signal On94Received Signal Off95Contrast Level96Excess Gain97	NameŠ p LReceived Signal On94Received Signal Off95O00Received Signal Off95O00Excess Gain97	NameX a b gX a b gX b gX b 	NameNameNameNameNameNameNameNameNameNameNameDataTypeReceived Signal On940UlntegerT_16Received Signal Off950UlntegerT_16Contrast Level960UlntegerT_8Excess Gain970UlntegerT_8	NameNameNameNameNameNameNameNameNameNameNameNameNameValues RangesReceived Signal On940UIntegerT_1600<	Received Signal On 94 0 UIntegerT_16 Received Signal Off 95 0 UIntegerT_16 Contrast Level 96 0 UIntegerT_8 Excess Gain 97 0 UIntegerT_8	NameNa	NameNa	NameXameXameXameXameXameXameValues RangesSingle valuesXameDefault ValueMReceived Signal On940UIntegerT_16rorororoReceived Signal Off950UIntegerT_16rorororoContrast Level960UIntegerT_8rorororoExcess Gain970UIntegerT_8rororo	NameNa

Tbl.:16

Observation.

Device Monitoring, data coming from the device.

Received Signal On: when the device is in Light status, it displays the average of the signals received by the active optics. When the device is in Dark status, it displays the last average of the signals received by the active optics before the assumption of the Dark state.

Received Signal Off: when the device is in the Dark status, it displays the average of the signals received by the active optics.

- When the device is in Light status, it displays the last average of the signals received by the active optics before the assumption of the Light state. Contrast Level: ratio between taught Light signal level (on reflector) and the current Dark signal.
- Excess Gain: ratio between the current Light signal and the Light threshold.
- Excess Gain Resolution: allows you to choose the data format. [0]: Displays the Excess Gain in units, factory set condition. [1]: Displays the Excess Gain in tenths.

					DIAGNOSI	S						
Variable ID	Name	Index	SubIndex	BitOffset	DataType	Values Ranges	Single values	Access	Default Value	м	D	E
Diagnosis (Displays Devic	ce Status)											
V_ErrorCount	Error Count	32	0		UIntegerT_16			ro			Х	
V_DeviceStatus	Device Status	36	0		UIntegerT_8	0-255	Device is OK (0), Maintenance required (1), Out of specification (2), Functional check (3), Failure (4) Reserved (5-255)	ro				
V_DetailedDeviceStatus	Detailed Device Status	37	0		ArrayT			ro			Х	
	Detailed Device Status [1]	37	1	72	OctetStringT [3]		0x00,0x00,0x00					
	Detailed Device Status [2]	37	2	48	OctetStringT [3]		0x00,0x00,0x00					
	Detailed Device Status [3]	37	3	24	OctetStringT [3]		0x00,0x00,0x00					
	Detailed Device Status [4]	37	4	0	OctetStringT [3]		0x00,0x00,0x00					

Tbl.:17

Diagnosis

Error Count: Return value. Displays communication errors.

Device Status: Return value. Messages displayed:

[0]: Device is OK (Device is operating properly)

[1]: Maintenance required (Component undergoing degradation or failure)

[2]: Out of specification (-10°C>Device Temperature out of range >80°C)

[3]: Functional check (Teach-in error, calibration failed due to poor signal level) [4]: Failure



CR SERIES IO-Link POLARIZED RETROREFLECTIVE SENSOR ARRAY **IO-LINK PARAMETER**

Language: EN Pages: 17 Code: 806001120 Date: 13/10/2023

DIAGNOSIS													
Variable ID	Name	Index	SubIndex	BitOffset	DataType	Values Ranges	Single values	Access	Default Value	м	D	E	
Service Function													
V_Standard Command	Restore Factory Setting	2	0		UIntegerT_8	130	130	wo		Х			
V_LocalIndicator	Local Indicator	99	0		UIntegerT_8	0, 1	Disabled (0), Enabled (1)	rw	0				
V_LEDOperation	LEDs Operation	100	0		UIntegerT_8	0, 1	Disabled (0), Enabled (1)	rw	0				
V_AlignmentMode	Alignment Mode	101	0		UIntegerT_8	0, 1	Disabled (0), Enabled (1)	rw	0				
V_LEDFromPD	LEDs control from Process Data	102	0		UIntegerT_8	0, 1	Disabled (0), Enabled (1)	rw	0				

Service Function .

Standard Command: Command, Restore Factory Settings (load the Default Values, see table(s)).

In the subsequent functions, the behavior is defined by the highest priority* (I*, II, III, IV); see also the table below.

- (III) Local Indicator: Active only if the highest priorities (I, II) are disabled: [0]: Disabled: Not active. Factory set condition.
 - [1]: Enabled: The Green and Red LEDs flash together with a duration of 0.5s and a period of 1s, with the aim of identifying the position of the device.
- (IV) LEDs Operation (rw); Drop down menu. Active only if the highest priorities (I, II, III) are disabled. [0]: Disabled: Not active.

[1]: Enabled: Factory set condition. All standard device functions enabled. The Green LED shows the IO-Link (SDCI) communication integrity flashing with a sequence of 0.9s ON and 0.1s OFF, or if not connected is ON steady. The Red LED lights up in the Dark state with an intensity directly proportional to the percentage of the optics in the Dark.

- (II) Alignment Mode: Active only if the highest priorities (I) are disabled. . [0]: Disabled: Not active. Factory set condition. [1]: Enabled: The Green LED shows a brightness proportional to the signal strength. The Red LED displays brightness inversely proportional to signal strength and simultaneously indicates IO-Link communication integrity (SDCI) by flashing ON or OFF, reversing steady state, with a duration of 0.1s and a period of 1s.

[I] LEDs control from Process Data. drop down menu. Highest priority.
[0]: Disabled: Not active. Factory set condition.
[1]: Enabled: The Green LED operates ON/OFF as specified in menu. The Red LED operates ON/OFF as specified in menu.

Se	Diagn ervice F		ı		cess ita iput	
- → H	IIPrio			LE	Ds	
		III	IV		-	
LED control from process data	Alignment mode	Local indicator	LED Operation	Green	Red	
Dis.	Dis.	Dis.	Dis.	OFF	OFF	Function performed
En.	En.	En.	En.	ON	ON	Function performed
Dis.	Dis.	Dis.	Dis.	OFF	OFF	No indication, Green and Red LED OFF
_				OFF	OFF	
En.	x	x	x	ON	ON	Full control of LEDs from Master (Data Process Output ON/OFF)
Dis.	En.	x	x	↑ Light	↑ Dark	Green LED is proportional to the Light; Red LED is proportional to Dark. The Red LED is also flashing indicating Device Connected.
Dis.	Dis.	En.	x	Flash ing	Flash ing	The Green and Red LED flash together to pinpoint the location of the device.
Dis.	Dis.	Dis.	En.	Flash ing	↑ Dark	Factory setting. The Green LED flashes to indicate connection. The red LED lights up in the Dark state with an intensity proportional to the optics in Dark.

Tbl.:19

	easing automation challenges Fax: +39 059 253973 www.datasensing.com		LAR	IZE	CR SER	,	Language: EN Pages: 17 Code: 806001120					
	info@datasensing.com			D					Date:	13/10/	2023	
Variable ID	Name	Index	SubIndex	BitOffset	DataType	Values Ranges	Single values	Access	Default Value	м	D	E
Operation Information												
V_OperationHoursInception	Operation Hours since Inception	104	0		UIntegerT_32	0 - 71582788		ro				
V_OperationHoursPowerUp	Operation Hours since Power-Up	105	0		UIntegerT_32	0 - 71582788		ro				
Temperature							Г			1		
V_Temperature	Temperarture	106	0		RecordT			ro			х	
dynamic parameter	Actual	106	1*		IntegerT_8	-128 to 127						
dynamic parameter	Max since Power-Up	106	2*		IntegerT_8	-128 to 127						
dynamic parameter	Max since Inception	106	3*		IntegerT_8	-128 to 127						
dynamic parameter	Min since Power-Up	106	4*		IntegerT_8	-128 to 127						
dynamic parameter	Min since Inception	106	5*		IntegerT_8	-128 to 127						
Speed												
V_SpeedActual	Actual	107	0		UIntegerT_16	0 to 833		ro				
V_SpeedMax	Max (since Power-Up)	108	0		UIntegerT_16	0 to 833		ro				
Event Configuration												
V_EventLocalThresholdEnable	Event on Local Threshold Change	109	0		UIntegerT_8	0, 1	Off (0), On (1)	rw				
V_EventLowMarginEnable	Event on Low Margin	110	0		UIntegerT_8	0, 1	Off (0), On (1)	rw				
V_EventTeachError	Event on Teach Error	116	0		UIntegerT_8	0, 1	Off (0), On (1)	rw				
V_EventTemperature	Event on Temperature	111	0		UIntegerT_8	0, 1	Off (0), On (1)	rw				
V_EventTemperatureLow	Temperature Event Trigger Low	112	0		IntegerT_8	-128 to 127		rw				
V_EventTemperatureHigh	Temperature Event Trigger High	113	0		IntegerT_8	-128 to 127		rw				
V_EventCounterEnable	Event on Counter	114	0		UIntegerT_8	0, 1	Off (0), On (1)	rw				
V_EventCounterCount	Event Counter Count	115	0		UIntegerT_16	0 to 4095		rw				
		1								1		

Tbl.:20

Operation Information

- 0 Operation Hours since Inception: Return value.
- Operation Hours since Power-Up: Return value. 0
- Temperature (internal device temperature).
 - 0
 - Temperature Actual: Return value. Temperature Max since Power-Up: return value. 0
 - Temperature Max since Inception: return value. 0
 - Temperature Min since Power-Up: return value. 0
 - Temperature Min since Inception: return value. 0

Speed

- Actual: return value. It indicates the number of Light/Dark switching occurred in the last second (Hz). Max since Power-Up: return value. The maximum occurrence of the above from the Power-UP. С
- 0

Event Configuration: all disabled in factory set condition.

Event on Local Threshold Change. [0]: OFF. Disabled.

[1]: ON. Activate an event if the Teach-in button or the Remote teach Input is used.

Event on Low Margin. [0]: OFF Disabled.

1]: ON.. Enabled: Triggers an event when the Margin Level crosses the indicated limit, see also "Margin Level Low Multiplier".

Event on Teach Error. [0]: OFF Disabled.

[1]: ON.. Enabled: Triggers an event when the Teach-in function does not finish correctly (the signal is not enough).

Event on Temperature.

[0]: OFF. Disabled

[1]: ON. Enabled: Triggers an event when the sensor temperature crosses the indicated temperature limits below.

- Temperature Event Trigger Liow (entered value of the minimum temperature allowed).
 Temperature Event Trigger High (entered value of the maximum temperature allowed).
 The Restore Factory Setting command sets these two values to 0, it is therefore advisable to introduce plausible values before activating the "Event on Temperature".

Event on Counter: [0]: OFF. Disabled

- [1]: ON. Enabled: Triggers an event if the count reaches the value entered below:

 - **Event Counter Count** 0

					EVENTS
Code dec.	Code	Туре	>> On << Off	Name	Description
6144	0x1800	Notification		Threshold Changed Locally	Threshold Changed Locally: Event occurs when the threshold is changed at the sensor (buttons or wire)
6176	0x1820	Warning	>>or<<	Low Margin	Event occurs when a Margin Low Alarm (Process Data) is issued
6192	0x1830	Notification		Teaching Error	Teaching Error: Event occurs upon teaching error
6208	0x1840	Notification		Count Reached	Event occurs when a set count is reached
16.928	0x4220	Warning	>>or<<	Temperature underrun	Device temperature underrun: Insulate device
16.912	0x4210	Warning	>>or<<	Temperature overrun	Device temperature overrun: Clear source of heat
Tbl •21		Noto: >> Mog	ne a Wa	rning has appeared: << M	oans the Warning has disappeared

	DATASENSING S.F. Strada S. Caterina, i 41122 Modena (Ita Tel: +39 059 4204' Fax: +39 059 2539 www.datasensing.c info@datasensing.c	235, ly) 11 73 :om	P	OLA	RIZED RETI	ROREFL	S IO-Link ECTIVE SENSOR A RAMETER	ARR/	AY Language: Pages: Code: 806 Date: 13/	EN 17 001		
			CON	ИPL	ETE IODD (CI	RO. CR1.	CR2)					
Variable ID	Name	Index	SubIndex	BitOffset	DataType	Values Ranges	Single values	Access	Default value	м	D	E
V_DirectParameters_1	Direct Parameters - Page 1	0			RecordT		00 0C 2B 11 C4 08 03 05 00 07 D2 00 00 00 00B	rw				
	Reserved	0			UIntegerT_8		1200					
	Master Cycle Time Min Cycle Time	0			UIntegerT_8		1200us 1200us			-	-	\vdash
	M-Sequence	0			UIntegerT_8		0x2B					
	Capability IO-Link Revision ID	0	5	88	UIntegerT_8		1.1				-	\square
	Process Data Input	0	6	80	UIntegerT_8		5 B					
	Length Process Data Output	0	7	7~	l lintagar T						-	
	Length				UIntegerT_8		8 b				╞	
	Vendor ID 1 Vendor ID 2	0			UIntegerT_8		0x0305				┢	-
	Device ID 1	0			UIntegerT_8							
	Device ID 2	0			UIntegerT_8							
	Device ID 3 Reserved	0			UIntegerT_8 UIntegerT_8	-				-	<u> </u>	—
	Reserved	0			UIntegerT_8						t	H
	Reserved System Command	0			UIntegerT_8	0 to 63, 132 to 159	Device Reset (128), Application Reset (129), Restore Factory Settings (x		
V_DirectParameters_2	Direct Parameters - Page 2	1	0		RecordT		130), Back-to-box (131)	rw			-	
	Device-specific	1	1	120	UIntegerT_8					1	+	
	Parameter 1 Device-specific	-		120	onteger _0					_	╞	_
	Parameter 2	1	2	112	UIntegerT_8							
	Device-specific	1	3	104	UIntegerT 8							
	Parameter 3 Device-specific		_							+	┢	\vdash
	Parameter 4	1	4	96	UIntegerT_8							
	Device-specific Parameter 5	1	5	88	UIntegerT_8							
	Device-specific Parameter 6	1	6	80	UIntegerT_8						-	
	Device-specific	1	7	72	2UIntegerT_8							
	Parameter 7 Device-specific	1	8		UIntegerT 8							
	Parameter 8 Device-specific	1	9		UIntegerT_8						+	
	Parameter 9 Device-specific	1	10								-	
	Parameter 10 Device-specific	1	10	40	UIntegerT_8					_	┢	
	Parameter 11	1	11	40	UIntegerT_8							
	Device-specific Parameter 12	1	12	32	UIntegerT_8							
	Device-specific	1	13	24	UIntegerT_8							
	Parameter 13 Device-specific	1	14		UIntegerT_8					+	┢	\exists
	Parameter 14 Device-specific	1	14	10	onneger 1_8					_	┢	
	Parameter 15	1	15	8	UIntegerT_8						L	Ш
	Device-specific Parameter 16	1	16	C	UIntegerT_8							
V_SystemCommand	System Command	2	0		UIntegerT_8	0 to 63, 132 to 159	Restore Factory Settings (130), Teach Background (160), Teach Target (161), Teach Standard (162), Teach Precision (163), Counter Reset (164), Timer Reset (165), Apply Margin Multiplier (166)	wo		x		
V_DeviceAccessLocks	Device Access Locks	12	0		RecordT			rw			F	口
	Local Parameterization	12	3	2	BooleanT		Locked (true), Unlocked (false)					
V_VendorName	Vendor Name	16	0		StringT [64]		10130 /	ro	DATASENSING S.R.L.	+	\vdash	\vdash
 V_VendorText	Vendor Text	17			StringT [64]				Easing automation challenges			
V_ProductName	Product Name	18	0		StringT [64]				CR0/0I-1V CR1/0I-1V CR2/0I-1V	-		\square
V_ProductID	Product ID	19	0		StringT [64]			ro		1	F	口
V_ProductText	Product Text	20	0		StringT [64]			ro	Retroreflective Area Sensor			
V_SerialNumber	Serial Number	21	0		StringT [16]	1		ro		1	1	H

	DATASENSING S.F Strada S. Caterina,	235,	CR SERIES IO-Link											
DATASENSING	41122 Modena (Italy) Tel: +39 059 420411			POLADIZED DETRODECI ECTIVE SENSOD ADDAY										
easing automation challenges	Fax: +39 059 2539	73				-	RAMETER		Code.	80600				
	info@datasensing.c	com			10-1				Date:	13/10/2	2023			
V_HardwareRevision	Hardware Revision	22 23	0		StringT [64]			ro						
V_FirmwareRevision	Firmware Revision Application-specific				StringT [64]			ro	***					
V_ApplicationSpecificTag	Тад	24	0		StringT [32]			rw *						
							Device is OK (0),							
V_DeviceStatus	Device Status	36	0		UIntegerT_8		Maintenance required (1), Out of specification (2), Functional check (3), Failure (4)	ro			x			
		22												
V_ErrorCount V DetailedDeviceStatus	Detailed Device Status	32 37	0		UIntegerT_16 ArrayT			ro ro			X			
	Detailed Device				OctetStringT [3]			10			~			
	Status [1]	37	1	12										
	Detailed Device Status [2]	37	2	48	OctetStringT [3]									
	Detailed Device	37	3	24	OctetStringT [3]									
	Status [3] Detailed Device				0.1.1									
	Status [4]	37	4	0	OctetStringT [3]									
	Process Data Input: Triggered, Proximity							[
V_ProcessDataInput	Alarm, Margin, Excess	40	0		RecordT			ro			х			
	Gain, Received Signal		* *		Dealest		false (false) two (to)				\square			
	Triggered Proximity Alarm	40 40	1* 2*		BooleanT BooleanT	<u> </u>	false (false), true (true) false (false), true (true)	╞┼			+			
	Margin Low Alarm	40	3*		BooleanT		false (false), true (true)							
	Excess Gain	40	4*	16	UIntegerT_8									
	Received Signal Strength	40	5*	C	UIntegerT_16									
/_ProcessDataOutput	Process Data Output	41	0		RecordT			ro			х			
	Pin 2 Output	41	1*		BooleanT		false (false), true (true)							
	Green LED	41 41	2* 3*		BooleanT		false (false), true (true)							
	Red LED	41	3*		BooleanT CR0 model		false (false), true (true)							
V_SetPointEmitter1	Set Point Emitter 1	64	0		UIntegerT_16	0 to 1023		rw		767				
/_SetPointEmitter2	Set Point Emitter 2	65	0		UIntegerT_16	0 to 1023		rw		767				
V_SetPointEmitter3 V SetPointEmitter4	Set Point Emitter 3 Set Point Emitter 4	66 67	0		UIntegerT_16 UIntegerT_16	0 to 1023 0 to 1023		rw rw		767 767				
			-		Added for CR1 m	1								
V_SetPointEmitter5	Set Point Emitter 5	68	0		UIntegerT_16	0 to 1023		rw		767				
V_SetPointEmitter6	Set Point Emitter 6	69	0		UIntegerT_16	0 to 1023		rw		767				
V_SetPointEmitter7	Set Point Emitter 7	131	0		UIntegerT_16	0 to 1023		rw		767				
V_SetPointEmitter8	Set Point Emitter 8	132	0		UIntegerT_16	0 to 1023		rw		767				
\/ CatDaintEmittar0	Set Point Emitter 9	150	0		Added for CR2 m	T T				767				
V_SetPointEmitter9 V SetPointEmitter10		150	0		UIntegerT_16	0 to 1023		rw		767				
V_SetPointEmitter11	Set Point Emitter 10 Set Point Emitter 11	151	0		UIntegerT_16 UIntegerT_16	0 to 1023 0 to 1023		rw		767	+ +			
V SetPointEmitter12	Set Point Emitter 11	152	0		UIntegerT_16	0 to 1023		rw rw		767				
V SetPointEmitter13	Set Point Emitter 12	153	0		UIntegerT_16	0 to 1023		rw		767				
/ SetPointEmitter14	Set Point Emitter 14	155	0		UIntegerT_16	0 to 1023		rw		767				
/ SetPointEmitter15	Set Point Emitter 15	156	0		UIntegerT 16	0 to 1023		rw		767				
V_SetPointEmitter16	Set Point Emitter 16	157	0		UIntegerT_16	0 to 1023		rw		767				
V_SetPointThreshold	Set Point Threshold	70	0		CR0 model	0.4- 4005				000				
Receiver1_1	Receiver 1_1	70	0		UIntegerT_16	0 to 4095		rw		900				
V_SetPointThreshold Receiver1_2	Set Point Threshold Receiver 1_2	71	0		UIntegerT_16	0 to 4095		rw		900				
V_SetPointThreshold Receiver2 2	Set Point Threshold Receiver 2 2	72	0		UIntegerT_16	0 to 4095		rw		900				
/_SetPointThreshold	Set Point Threshold	73	0		UIntegerT_16	0 to 4095		rw		900	+			
Receiver2 3		/3	0		Sinceger 10	0 10 4095				500	+			
	Receiver 2_3					I	1	m44						
	Receiver 2_3 Set Point Threshold Receiver 3 3	74	0		UIntegerT_16	0 to 4095		rw		900				
/_SetPointThreshold Receiver3_3 /_SetPointThreshold	Set Point Threshold Receiver 3_3 Set Point Threshold	74 75	0		UIntegerT_16 UIntegerT_16	0 to 4095 0 to 4095		rw		900 900				
/_SetPointThreshold Receiver3_3 /_SetPointThreshold Receiver3_4	Set Point Threshold Receiver 3_3					0 to 4095								
/_SetPointThreshold Receiver3_3 /_SetPointThreshold	Set Point Threshold Receiver 3_3 Set Point Threshold Receiver 3_4 Set Point Threshold				UIntegerT_16	0 to 4095								
/_SetPointThreshold Receiver3_3 /_SetPointThreshold Receiver3_4 /_SetPointThresholdReceiver4_4	Set Point Threshold Receiver 3_3 Set Point Threshold Receiver 3_4 Set Point Threshold Receiver 4_4 Set Point Threshold	75	0		UIntegerT_16 Added for CR1 m UIntegerT_16	0 to 4095 odel 0 to 4095		rw		900 900				
/_SetPointThreshold Receiver3_3 /_SetPointThreshold Receiver3_4 /_SetPointThresholdReceiver4_4 /_SetPointThresholdReceiver4_5	Set Point Threshold Receiver 3_3 Set Point Threshold Receiver 3_4 Set Point Threshold Receiver 4_4 Set Point Threshold Receiver 4_5	75 123 124	0		UIntegerT_16 Added for CR1 m UIntegerT_16 UIntegerT_16	0 to 4095 0 to 4095 0 to 4095 0 to 4095		rw rw rw		900 900 900				
/_SetPointThreshold Receiver3_3 /_SetPointThreshold Receiver3_4 /_SetPointThresholdReceiver4_4 /_SetPointThresholdReceiver4_5	Set Point Threshold Receiver 3_3 Set Point Threshold Receiver 3_4 Set Point Threshold Receiver 4_4 Set Point Threshold Receiver 4_5 Set Point Threshold Receiver 5_5	75	0		UIntegerT_16 Added for CR1 m UIntegerT_16	0 to 4095 odel 0 to 4095		rw		900 900				
/_SetPointThreshold Receiver3_3 /_SetPointThreshold Receiver3_4 /_SetPointThresholdReceiver4_4	Set Point Threshold Receiver 3_3 Set Point Threshold Receiver 3_4 Set Point Threshold Receiver 4_4 Set Point Threshold Receiver 4_5 Set Point Threshold	75 123 124	0		UIntegerT_16 Added for CR1 m UIntegerT_16 UIntegerT_16	0 to 4095 0 to 4095 0 to 4095 0 to 4095		rw rw rw		900 900 900				

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V SetPointThresholdReceiver6 7	Set Point Threshold Receiver 6_7	128	0		UIntegerT_16	0 to 4095		rw	90	0		
	Set Point Threshold Receiver 7 7	129	0		UIntegerT_16	0 to 4095		rw	90	0		
V_SetPointThresholdReceiver7_8	Set Point Threshold Receiver 7_8	130	0		UIntegerT_16	0 to 4095		rw	90	0		
V SetPoint I breshold Receiver 8 8	Set Point Threshold Receiver 8 8	133	0	,	Added for CR2 m UIntegerT_16	odel 0 to 4095		rw	90	0		
V SetPointThresholdBeceiver8 9	 Set Point Threshold	134	0		UIntegerT_16	0 to 4095		rw	90	0		
V SetPointThresholdBeceiver9 9	Receiver 8_9 Set Point Threshold	135	0		UIntegerT_16	0 to 4095		rw	90	0		
V SetPointThresholdBeceiver9 10	Receiver 9_9 Set Point Threshold Receiver 9 10	136	0		UIntegerT_16	0 to 4095		rw	90	0		
V_SetPointThresholdReceiver10_10	Set Point Threshold Receiver 10 10	137	C		UIntegerT_16	0 to 4095		rw	90	0	T	
V_SetPointThresholdReceiver10_11	Set Point Threshold Receiver 10 11	138	0		UIntegerT_16	0 to 4095		rw	90	0	T	
V_SetPointThresholdReceiver11_11	Set Point Threshold Receiver 11 11	139	0		UIntegerT_16	0 to 4095		rw	90	0		
V_SetPointThresholdReceiver11_12	Set Point Threshold Receiver 11 12	140	0		UIntegerT_16	0 to 4095		rw	90	0		
V_SetPointThresholdReceiver12_12	Set Point Threshold Receiver 12 12	141	0		UIntegerT_16	0 to 4095		rw	90	0	╈	+
V_SetPointThresholdReceiver12_13	Set Point Threshold Receiver 12 13	142	C		UIntegerT_16	0 to 4095		rw	90	0	+	+
V_SetPointThresholdReceiver13_13	Set Point Threshold Receiver 13 13	143	C		UIntegerT_16	0 to 4095		rw	90	0		\top
V_SetPointThresholdReceiver13_14	Set Point Threshold Receiver 13 14	144	0		UIntegerT_16	0 to 4095		rw	90	0	╈	
V_SetPointThresholdReceiver14_14	Set Point Threshold Receiver 14 14	145	0		UIntegerT_16	0 to 4095		rw	90	0		
V_SetPointThresholdReceiver14_15	Set Point Threshold Receiver 14 15	146	0		UIntegerT_16	0 to 4095		rw	90	0		
V_SetPointThresholdReceiver15_15	Set Point Threshold Receiver 15 15	147	0		UIntegerT_16	0 to 4095		rw	90	0		
V_SetPointThresholdReceiver15_16	Set Point Threshold Receiver 15 16	148	0		UIntegerT_16	0 to 4095		rw	90	0		
V_SetPointPolarity	Polarity	76	0		UIntegerT_8		Not Inverted (LO) (0), Inverted (DO) (1)	rw		0		╈
V_OutputMode V SetPointHysteresis	Output Mode Hysteresis	77 78	0		UIntegerT_8 UIntegerT_16		PNP (0), NPN (1)	rw ro		0		
-	Pin 2 Mode	79	C		UIntegerT_8		Disable (0), PNP (LO) (1), PNP (DO) (2), NPN (LO) (3), NPN (DO) (4), Remote Teach Input (5), IndependentOuput PNP (6), IndependentOuput NPN (7)	rw		0		
					Only for the CR0 I	nodel	AND SixBeam (0), AND			T	1	1
V_BeamMode	Beam Mode	80	C		UIntegerT_8 Only for the CR1 1	nodel	AND SIXBEAM (0), AND FiveBeam (1), AND ThreeBeam (2), AND ThreeBeam (3), AND TwoBeam (4), AND OneBeam (4), AND OneBeam (5), OR SixBeam (8), OR FiveBeam (9), OR FourBeam (10), OR ThreeBeam (11), OR TwoBeam (12), OR OneBeam (13)	rw		0 x		
					Only for the CR1 I	nodel	AND FourteenBeam (0			Т		
V_BeamMode	Beam Mode	80	C	,	UIntegerT_8), AND ThirteenBeam (1), AND TwelveBeam (2), AND ElevenBeam (3), AND TenBeam (4), And NineBeam (5), AND EightBeam (6), AND SevenBeam (7), AND SixBeam (8), AND FiveBeam (1), AND ThreeBeam (10), AND ThreeBeam (11), AND TwoBeam (12), AND OneBeam (13),	rw		0 x		
							OR FourteenBeam (16), OR TirteenBeam (17), OR TwelveBeam (18), OR ElevenBeam (19), OR TenBeam (20), OR NineBeam (21), OR					

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easing automation challenges	www.datasensing.c	om			10-L	INK PA	RAMETER		Date:	13/10			
					Only for the CR2 n	nodel	EightBeam (22), OR SevenBeam (23), OR SixBeam (24), OR FiveBeam (25), OR FourBeam (26), OR ThreeBeam (27), OR TwoBeam (28), OR OneBeam (29)						
							AND ThirtyBeam (0),						1
V_BeamMode	Beam Mode	80	0		UIntegerT_8		AND TwentynineBeam (1), AND TwentyeightBeam (2), AND TwentysvevenBeam (3), AND TwentysixBeam (4), AND TwentyfiveBeam (5), AND TwentyfiveBeam (6), AND TwentythreeBeam (7), AND TwentythreeBeam (8), AND TwentytoneBeam (8), AND TwentytoneBeam (10), AND Twentybeaem (11), AND EighteenBeam (11), AND EighteenBeam (12), AND SixteenBeam (12), AND SixteenBeam (12), AND SixteenBeam (13), AND FiretenBeam (16), AND ThirteenBeam (17), AND TwelveBeam (18), AND TelevenBeam (21), AND TelevenBeam (22), AND ThirteenBeam (23), AND FiveBeam (24), AND FiveBeam (24), AND FiveBeam (25), AND FourBeam (27), AND ThreeBeam (27), AND ThreeBeam (28), AND OneBeam (29), OR ThirtyBeam (32), OR TwentysineBeam (34), OR TwentysevenBeam (35), OR TwentyfourBeam (37), OR TwentyfourBeam (37), OR TwentyfourBeam (37), OR TwentyfourBeam (33), OR TwentyfourBeam (34), OR TwentyfourBeam (44), OR SeventeenBeam (44), OR SeventeenBeam (44), OR FourteenBeam (44), OR FourteenBeam (44), OR FiteenBeam (44), OR TirdenBeam (55), OR FiteenBeam (45), OR TirdenBeam (55), OR FiteenBeam (55), OR FiteenBeam (55), OR FiveBeam (5	rw		0	x		

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PACY Peasing automation challenges				ULA		RRAT	Code: 806001120					
	info@datasensing.c	om			10-		RAMETER		Date:	13/10)/20	23
							FourBeam (58), OR ThreeBeam (59), OR TwoBeam (60), OR OneBeam (61)					
V_MarginBoosterProposed	Margin Booster Proposed	81	0		UIntegerT_8	10 to 100		rw		10	х	
V MarginBoosterApplied	Applied Margin	82	0		UIntegerT 8	10 to 200		ro				
V_MarginLevelLowMultiplier	Margin Level Low	83	0		UIntegerT_8		0.8 (0), 0.7 (1), 0.6 (2),	rw		0		
V_MarginLevelHighMultiplier	Multiplier Margin Level High Multiplier	84	0		UIntegerT_8		0.5 (3) 1.0 (10), 1.1 (11), 1.2 (12), 1.5 (15), 2.0 (20), 5.0 (50), 10.0 (100), 15.0	rw		12		
N. CounterFactula	Counton Frankla	05	0		Lunta na T		(150) Disabled (0) Suchlad (1)			0		
V_CounterEnable	Counter Enable	85			UIntegerT_8	0.1 4005	Disabled (0), Enabled (1)	rw		0		
V_CounterValue V_WorkingFrequency	Counter Value Working Frequency	86 87	0		UIntegerT_16 UIntegerT_8	0 to 4095	1(0),2(1)	ro rw		0		
V TimerEnable	Timer	88	0		UIntegerT_8		Disabled (0), Enabled (1)	rw		0		
V_TimerMode	Timer Mode	89	0		UIntegerT_8		On Delay (0), Off Delay (1), One Shot (3), Timer Duration (4)	rw		0		
V_TimerValue	Timer Value	90	0		UIntegerT_16	0 to 50000		rw		0		
 V_TimerOnDuration	Timer On Duration	91	0		UIntegerT_16	0 to 4095		ro				
V_TimerOffDuration	Timer Off Duration	92	0		UIntegerT_16	0 to 4095	CR0, CR1, CR2	ro				+
V_ProcessDataInMode	Process Data In Mode	93	0		UIntegerT_8		Output, Proximity Alarm, Margin, (0, 1, 2, 3, 4). Excess Gain, (0, 1). Received Signal (0). Contrast Level, Temperature (1). Counter (3). Timer Off Duration, Timer On Duration (4). CR0, CR1 Beam status, Speed (2). Excess Gain (3). CR2 Beam status High, Beam status Low (2). Speed (3).	rw		0		
V_ReceivedSignalOn	Received Signal On	94	0	-	UIntegerT_16			ro				
V_ReceivedSignalOff V ContrastLevel	Received Signal Off Contrast Level	95 96	0		UIntegerT_16 UIntegerT_8			ro ro				
V_ExcessGain	Excess Gain	97	0		UIntegerT_8			ro				
V_ExcessGainResolution	Excess Gain Resolution	98	0		UIntegerT_8		1.0 (0), 0.1 (1)	rw		0		
V_LocalIndicator	Local Indicator	99	0		UIntegerT_8		Disabled (0), Enabled (1)	rw		0		
V_LEDOperation	LEDs Operation	100	0		UIntegerT_8		Enabled (0), Disabled (1)	rw		0		
V_AlignmentMode	Alignment Mode	101	0		UIntegerT_8		Disabled (0), Enabled (1)	rw		0		
V_LEDFromPD	LEDs control from Process Data	102	0		UIntegerT_8		Disabled (0), Enabled (1)	rw		0		
V_OperationHoursInception	Operation Hours since	104	0		UIntegerT_32	0 to		ro				
V OperationHoursPowerUp	Inception Operation Hours since	105	0		UIntegerT_32	71582788 0 to		ro				
V_Temperature	Power-Up Temperarture	105	0		RecordT	71582788		ro				х
	Actual	106	1*	32	IntegerT_8	-128 to		10				^
	Max since Power-Up	106	2*		IntegerT 8	127 -128 to						
	Max since Inception	106	- 3*		IntegerT_8	127 -128 to 127						
	Min since Power-Up	106	4*	8	IntegerT_8	-128 to 127						
	Min since Inception	106	5*	0	IntegerT_8	-128 to 127						
V_SpeedActual	Actual	107	0		UIntegerT_16	0 to 833		ro				
V_SpeedMax	Max (since Power-Up)	108	0		UIntegerT_16	0 to 833		ro				\square
V_EventLocalThresholdEnable	Event on Local Threshold Change	109	0		UIntegerT_8		Off (0), On (1)	rw		0		
V_EventLowMarginEnable	Event on Low Margin	110	0	_	UIntegerT_8		Off (0), On (1)	rw		0		
V_EventTemperature	Event on Temperature	111	0		UIntegerT_8		Off (0), On (1)	rw		0		
V_EventTemperatureLow	Temperature Event Trigger Low Temperature Event	112	0		IntegerT_8	-128 to 127 -128 to		rw		0		
V_EventTemperatureHigh	Trigger High	113	0		IntegerT_8	127		rw		0		
V_EventCounterEnable	Event on Counter	114	0		UIntegerT_8		Off (0), On (1)	rw		0		
V_EventCounterCount	Event Counter Count	115	0		UIntegerT_16			rw		0		
V_EventTeachError V_UserTag1	Event on Teach Error	116 120	0		UIntegerT_8 StringT [16]		Off (0), On (1)	rw		0		+
V_UserTag1 V UserTag2	User Tag 1 User Tag 2	120	0		String [16] StringT [16]			rw rw				
Tbl.:22			0	1		1	1					



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Timer functions

